

The geometry of spheres in free abelian groups

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joint work with Samuel Lelièvre and Christopher Mooney

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Introduction

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We will study sphere-averages:

$$\lim_{n \rightarrow \infty} \frac{1}{|S_n|} \sum_{x \in S_n} \frac{1}{n} f(x).$$

Cone measure

Given finite genset (\mathbb{Z}^d, S) ,

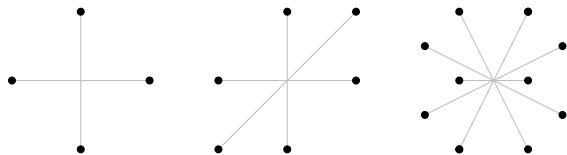


Figure: Some gensets: $S_{\text{std}} = \pm\{e_1, e_2\}$, $S_{\text{hex}} = \pm\{e_1, e_2, e_1 + e_2\}$,
 $S_{\text{chess}} = \{(\pm 2, \pm 1), (\pm 1, \pm 2)\}$ (with irrelevant generator thrown in).

Cone measure

Given finite genset (\mathbb{Z}^d, S) , let Q be the convex hull of S in \mathbb{R}^d ,

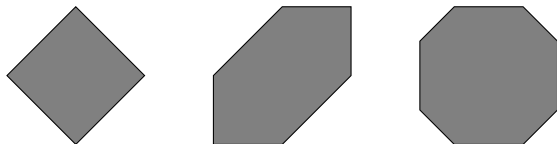


Figure: Convex hulls Q .

Cone measure

Given finite genset (\mathbb{Z}^d, S) , let Q be the convex hull of S in \mathbb{R}^d , let $L = \partial Q$,

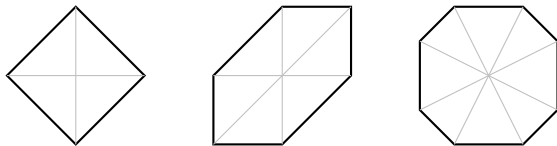


Figure: Boundary polyhedra L .

Cone measure

Given finite genset (\mathbb{Z}^d, S) , let Q be the convex hull of S in \mathbb{R}^d , let $L = \partial Q$, and let \hat{A} be the cone from $A \subseteq L$ to $\mathbf{0}$, so that $Q = \hat{L}$.

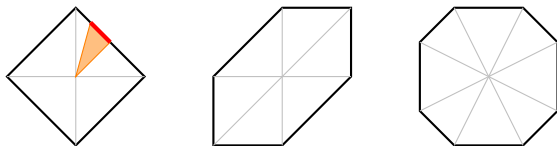


Figure: A cone.

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Define the *cone measure* by $\mu(A) = \mu_L(A) = \frac{\text{Vol}(\hat{A})}{\text{Vol}(Q)}$.

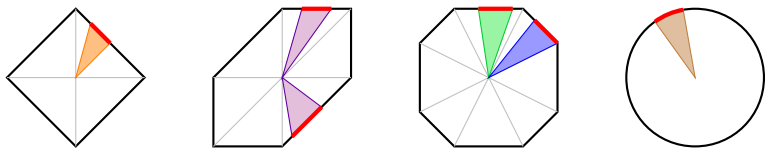


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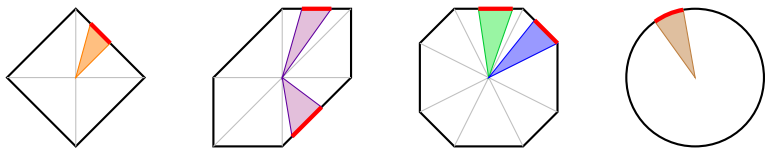


Figure: Cone measure.

As we will discuss below, $\frac{1}{n}S_n \rightarrow L$ as a Gromov-Hausdorff limit. We show *counting measure on spheres converges to cone measure on L* .

Limit shape, limit measure

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Theorem (Limit shape and limit measure)

For any finite presentation (\mathbb{Z}^d, S) and any function $f : \mathbb{Z}^d \rightarrow \mathbb{R}$ asymptotic to a homogeneous $g : \mathbb{R}^d \rightarrow \mathbb{R}$,

$$\lim_{n \rightarrow \infty} \frac{1}{|S_n|} \sum_{x \in S_n} \frac{1}{n} f(x) = \int_L g(x) d\mu(x).$$

So group averaging problem reduces to a problem in convex geometry.

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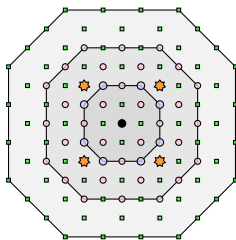


Figure: The *chess-knight metric*.

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- The annular region $\Delta_n L := nQ \setminus (n-1)Q$ is covered by $S_{n-1} + Q$.
- How much word-length is used to fill in Q ? Let $K = \max |\mathbb{Z}^2 \cap Q|$.
Then $|w|$ and $\|w\|_L$ differ by at most K . (Burago 1992)

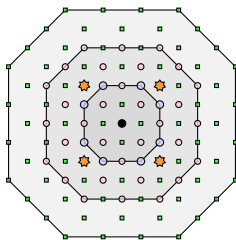
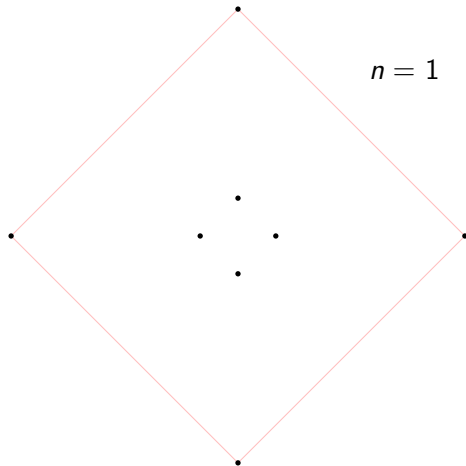


Figure: The *chess-knight metric*.

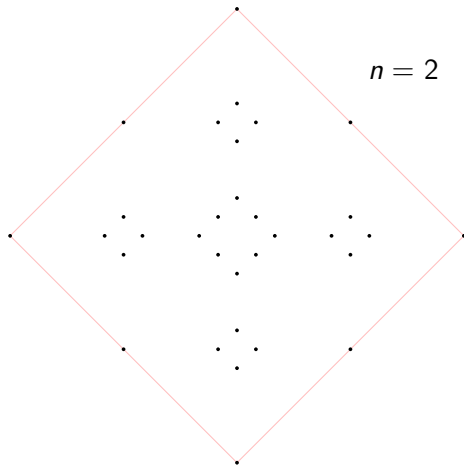
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\mathbb{Z}^2 with $S = \{6e_1, e_1, 6e_2, e_2\}$. Watch $\frac{1}{n} S_n$ converge to L .



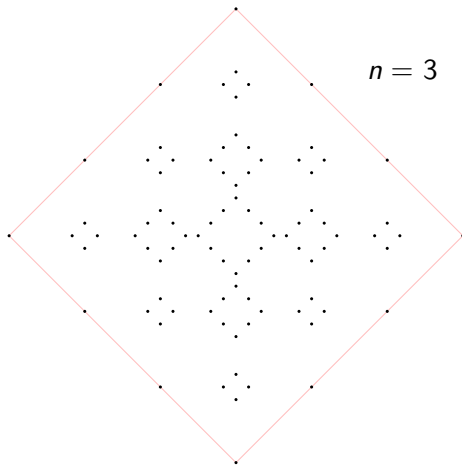
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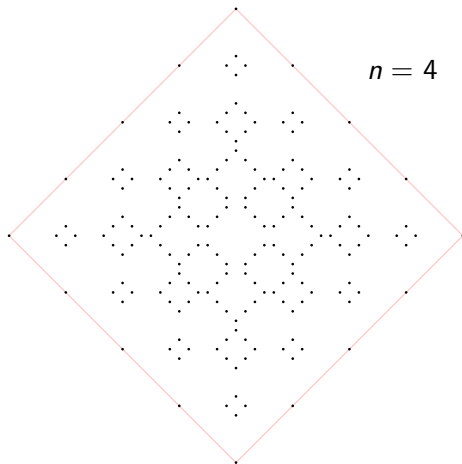
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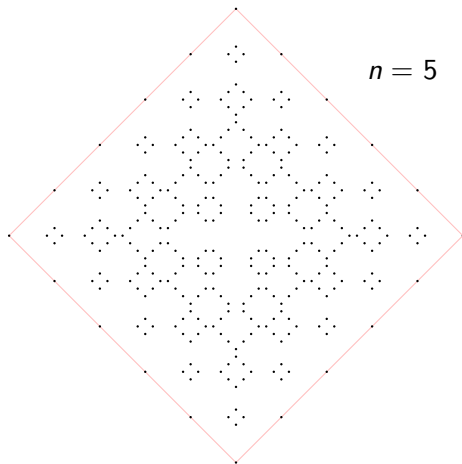
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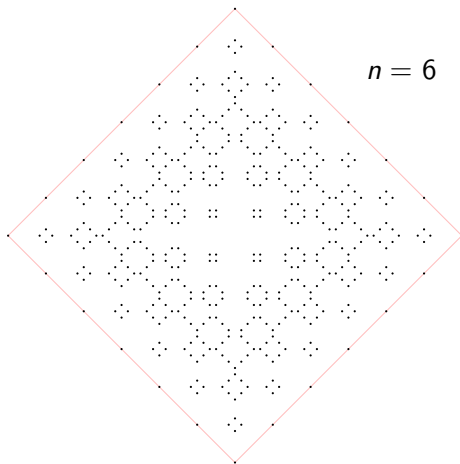
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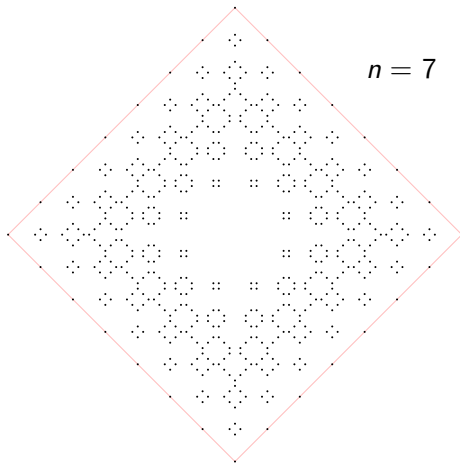
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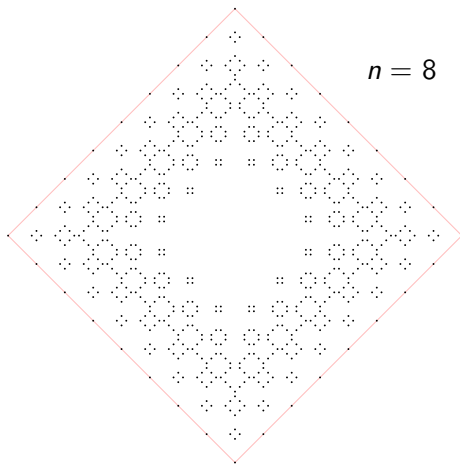
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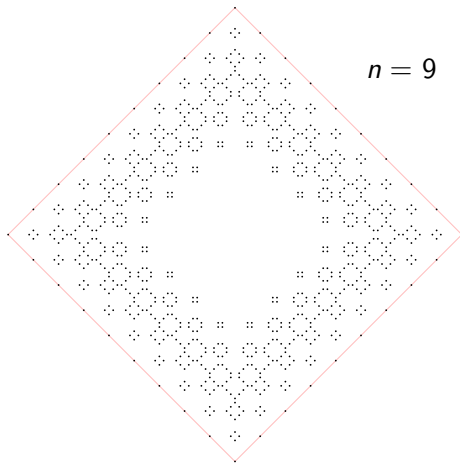
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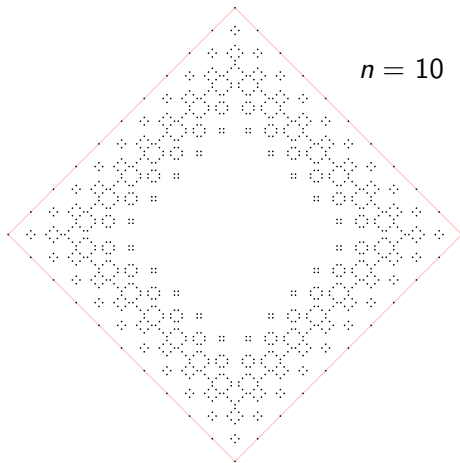
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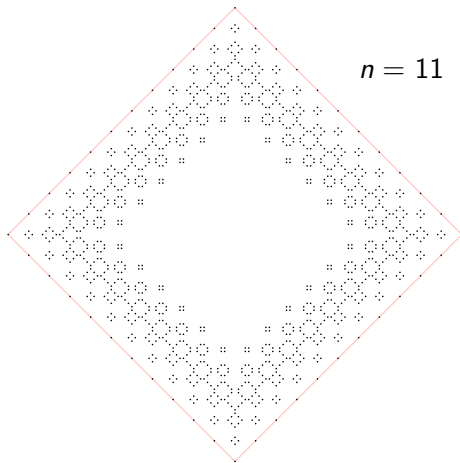
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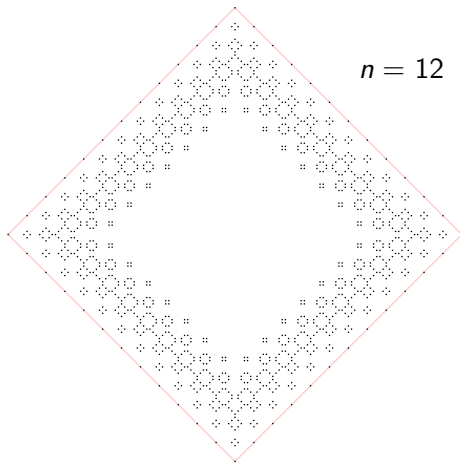
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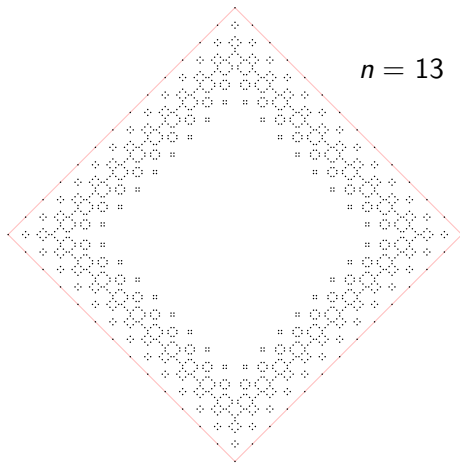
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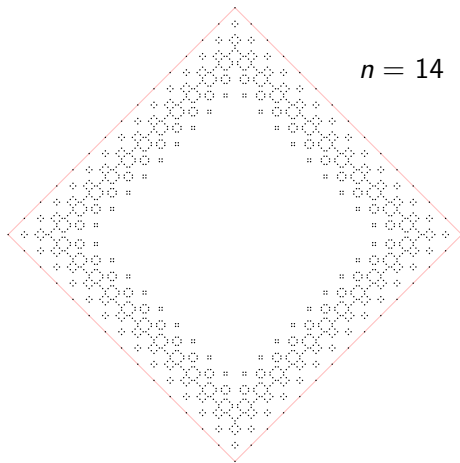
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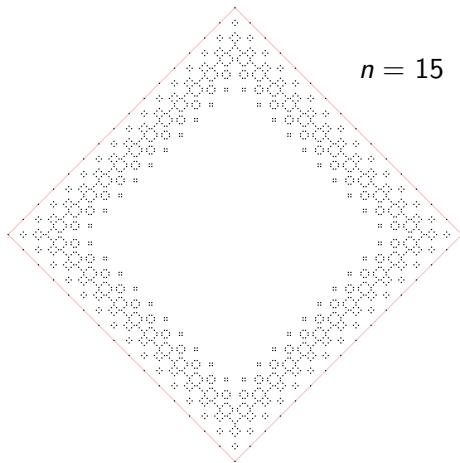
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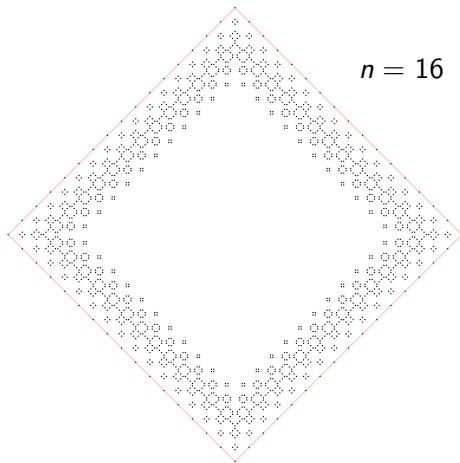
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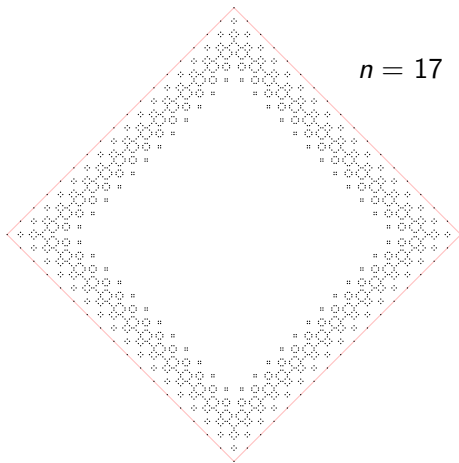
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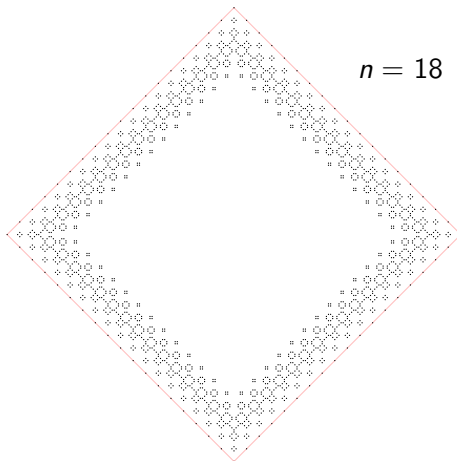
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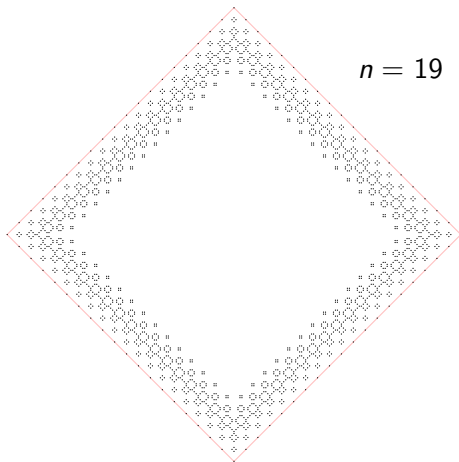
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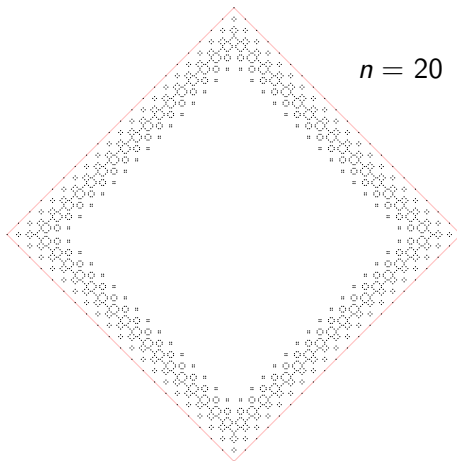
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Application: Density

Theorem (Density)

For any asymptotically homogeneous function $f : \mathbb{Z}^d \rightarrow \mathbb{R}$,

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Notably different from scale-invariant functions on \mathbb{Z}^d , or from any functions on hyperbolic groups, where ball-average equals sphere-average.

Introducing *sprawl*

Question: what is the average distance between two points in a large sphere?

$$E(G, S) := \lim_{n \rightarrow \infty} \frac{1}{|S_n|^2} \sum_{x, y \in S_n} \frac{1}{n} d(x, y).$$

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Note $E(L) = E(TL)$ for $L \in GL(d, \mathbb{R})$.

Sprawl in \mathbb{Z}^2

We developed the *cutline* algorithm for computing sprawls of polygons and used it to make calculations, showing the extent of dependence on S .



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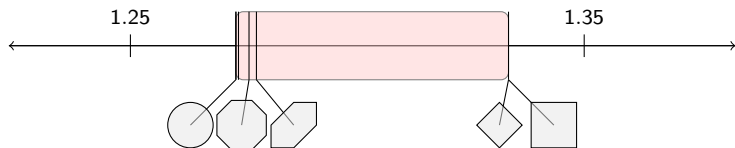


Figure: Ranges of sprawls.

Sprawls of hexagons and three-generator presentations

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Besides lots of empirical evidence, here is some good rigorous evidence.

Theorem

$$\{E(H) : \text{hexagons } H\} = [23/18, 4/3].$$

Thus, $\frac{23}{18} \leq E(\mathbb{Z}^2, S) \leq \frac{4}{3}$ whenever $|S| \leq 6$.

Sprawl in \mathbb{Z}^d

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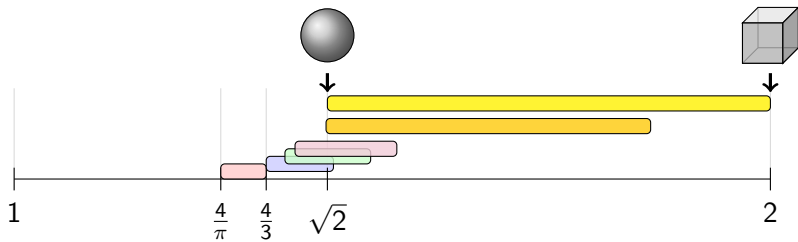


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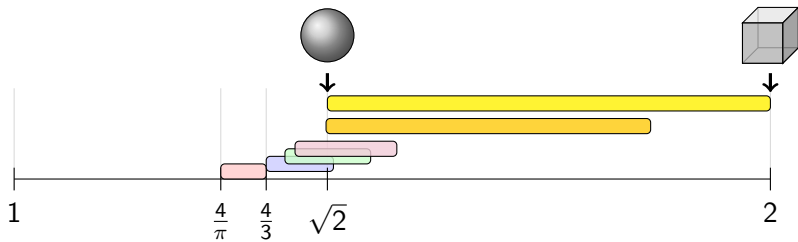


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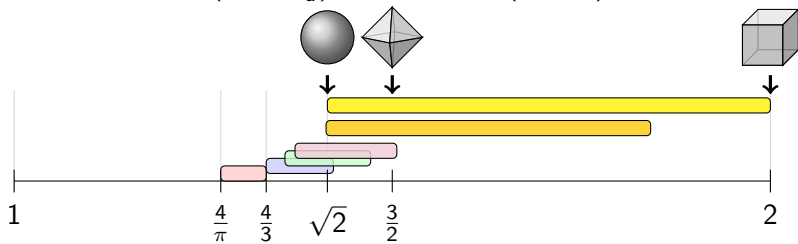


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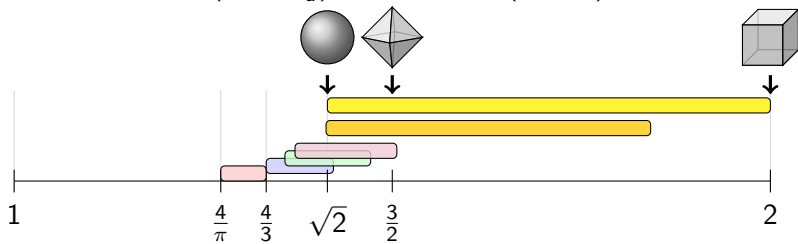


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Conclusion: to make a free abelian group look as hyperbolic as possible, use the nonstandard generators $S_{\text{cube}} = \{\pm e_1 \pm e_2 \cdots \pm e_d\}$.